

# T-61.6040 Assignment-02/2011

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## AIM

Implementation of support vector regression algorithm discussed in the lecture using Gaussian kernel for a motorcycle dataset.

$$k_{GAU} = (x_i, x_j) = \exp(-\|x_i x_j\|_2^2 / s^2), C = 100, \text{ and } s = \{0.0625, 0.25, 1, 4, 16\}; \text{ and } \epsilon = 16. \quad (1)$$

$$k_{GAU} = (x_i, x_j) = \exp(-\|x_i x_j\|_2^2 / s^2), C = 100, \text{ and } s = 1 \text{ and } \epsilon = \{1, 4, 16, 64, 256\} \quad (2)$$

## Datasets

Motorcycle dataset for regression analysis.

## Implementation

Load and zscore normalize both the X and Y data using zscore matlab command. Zscore normalization can also be done using the method described in the lecture.

```
X = zscore(dlmread('motorcycle_X.txt'));  
y = dlmread('motorcycle_y.txt');
```

Calculate Gaussian kernel function.

```
K = exp(-bsxfun(@plus, sum(X.^2, 2), ...  
                bsxfun(@plus, sum(X.^2, 2)', -2.*X*X')))./(S(k).^2);
```

Solve SVR optimization problem in standard QP form using quadprog function in matlab and find alpha values.

```

H = [+K, -K; -K, +K];
A = [];
Aeq = [+ones(N, 1); -ones(N, 1)]';
l = zeros(2 * N, 1);
c = [epsilon * ones(N, 1) - y; epsilon * ones(N, 1) + y];
b = [];
beq = 0;
u = C * ones(2 * N, 1);
options = optimset('Algorithm','interior-point-convex','MaxIter',1500);
% solve quadprog to find alpha values
alpha = quadprog(H, c, A, b, Aeq, beq, l, u, [], options);
% calculate near boundary coefficients

```

Compute the near boundary coefficients and move near boundary alpha values to boundaries. And also separate the alpha positives and alpha negatives.

```

alpha(alpha < C * (eps)) = 0;
alpha(alpha > C * (1-eps)) = C;
alphap = alpha(1:133,1);
alphan = alpha(134:266,1);

```

Compute value for bias parameter b

```

svp = find(alphap > 0 & alphap < C);
svp_one = zeros(N,1);
svp_one(sv,1) = 1; % (alpha(alphap > 0 & alphap < C));
b = (svp_one' * (Y - (((alphap - alphan)' * K') - epsilon))) / (sum(svp_one));

```

Compute the decision function on training set

```

Ki = X(sv,:) * X';
temp = bsxfun(@plus, Ki' * (alpha(sv,:) * Y(sv,:)), b);

```

Compute the decision function on test set

```

Ki = exp(-bsxfun(@plus, sum(X(sv,:).^2,2), ...
bsxfun(@plus, sum(X.^2,2)', -2.*X(sv,:) * X')) ./ (S(k).^2));
yi = bsxfun(@plus, (Ki' * (alphap(sv,:) - alphan(sv,:))), b);

```

Plot the graphs showing different hyperplanes.

```

figure(k);
plot(X,Y,'+', 'linewidth',1); hold on
plot(X(sv,1),Y(sv,1), 'o', 'linewidth',1);
[X_r idx] = sort(X);
plot(X_r, yi(idx,:), 'k-', 'linewidth',2);
title(['epsilon = 16, S = ', num2str(S(k))]);
%—print figure—
fnout = ['S=', num2str(k, '%.2d'), '.jpg'];
print('-djpeg', '-r150', fnout);

```

The Gaussian kernel implementation is carried out for all the values of  $s = \{0.0625, 0.25, 1, 4, 16\}$ ; and  $\epsilon = 16$  and these plots are shown in figure 1.

similarly the same implementation is carried out for all the values of  $s = 1$  and  $\epsilon = \{1, 4, 16, 64, 256\}$  and these plots are shown in figure 2.

Running of code for Gaussian kernel in matlab for case1 and case2 are as svr1 and svr2 respectively.

## Results

Figure 1 shows that the  $S$  value increases the gaussian kernel behaves more like a linear kernel. With the smaller  $S$  value the small Gaussian distribution is actually seen properly. As the  $S$  increases the width of the Gaussian distribution tends to increase.

Figure 1 shows that the  $\epsilon$  value is significantly large the gaussian kernel behaves more like a linear kernel. With the smaller  $\epsilon$  value there is not much change in the hyperplane but large significant

## References

- [1] Chapter 9 Scholkopf and Smola (2002)
- [2] [http://en.wikipedia.org/wiki/Support\\_vector\\_machine](http://en.wikipedia.org/wiki/Support_vector_machine)
- [3] <http://www.mathworks.se/help/toolbox/optim/ug/quadprog.html>

## Attachments

Matlab code svr1.m and svr2.m and datasets have been archived along with this report.

Figure 1: Plots showing the hyperlane separations for different cases of  $S$ .



